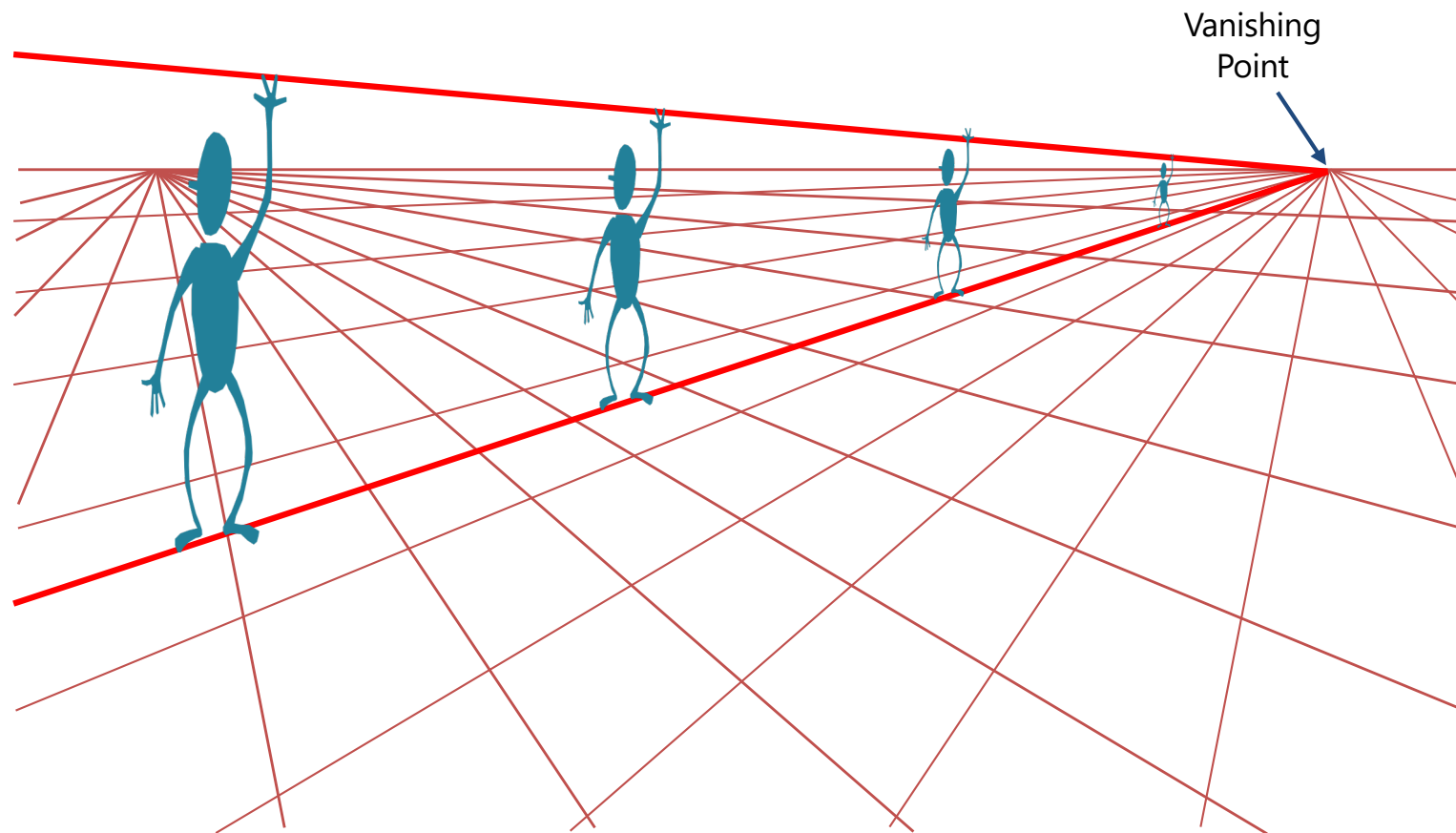


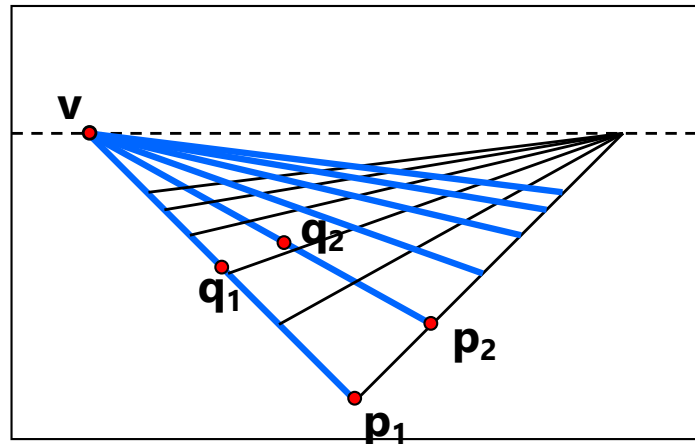
Folien zur Vorlesung am 8.04.2025
3D Computer Vision

DEPTH FROM A SINGLE IMAGE

Comparing heights



Computing vanishing points (from lines)



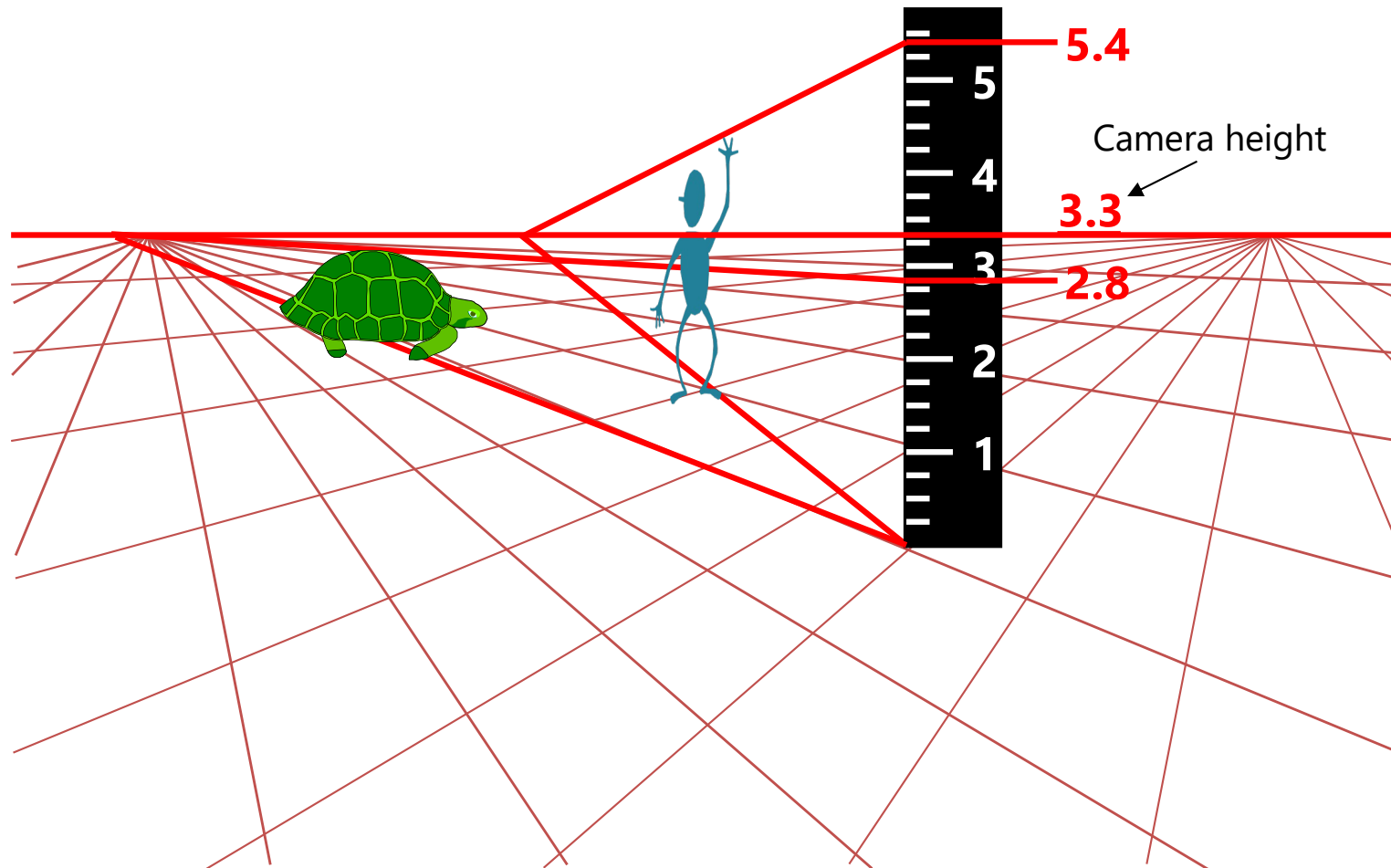
Intersect p_1q_1 with p_2q_2

$$v = (p_1 \times q_1) \times (p_2 \times q_2)$$

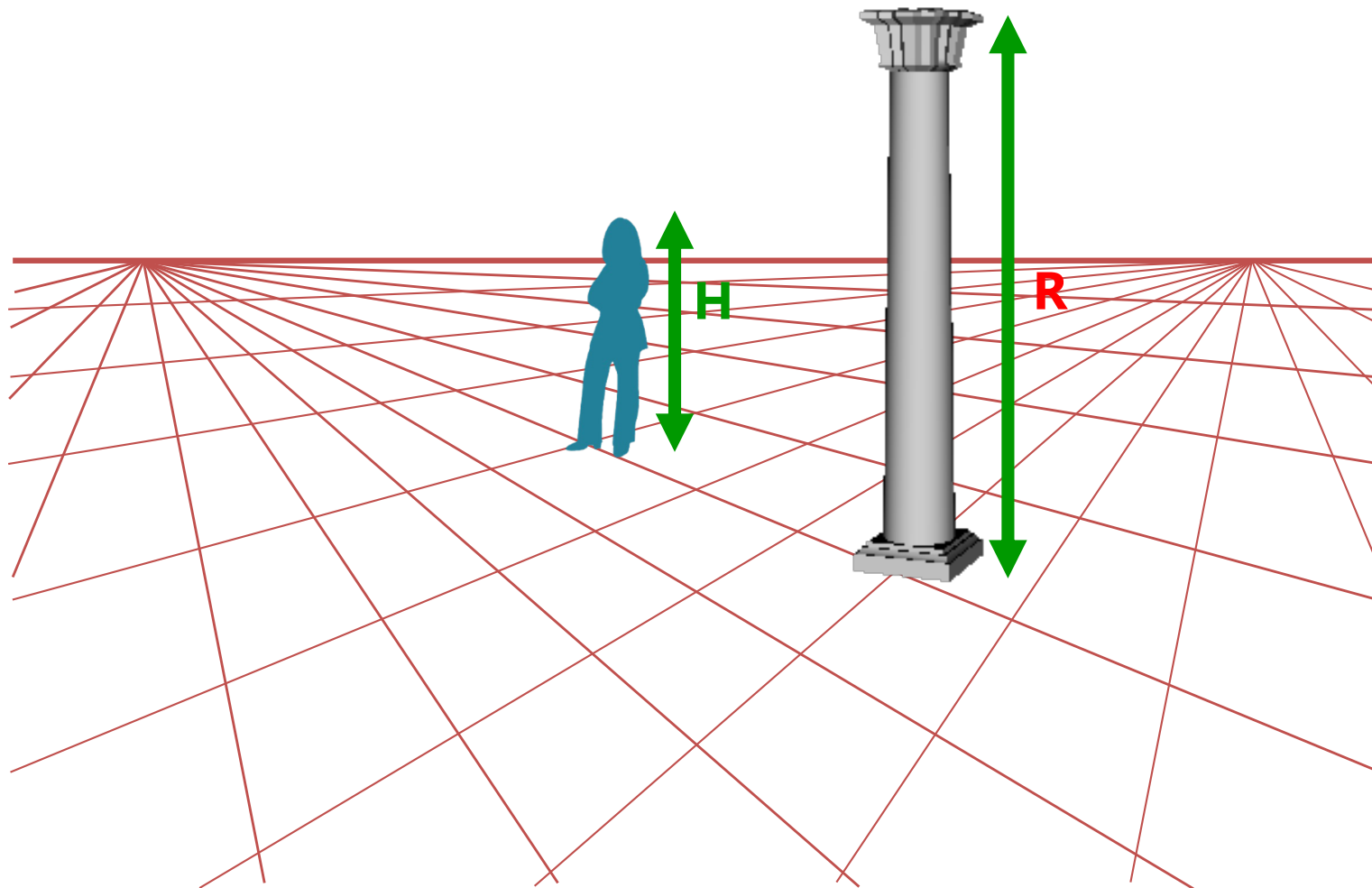
Least squares version

- Better to use more than two lines and compute the "closest" point of intersection
- See notes by [Bob Collins](#) for one good way of doing this:
 - <http://www-2.cs.cmu.edu/~ph/869/www/notes/vanishing.txt>

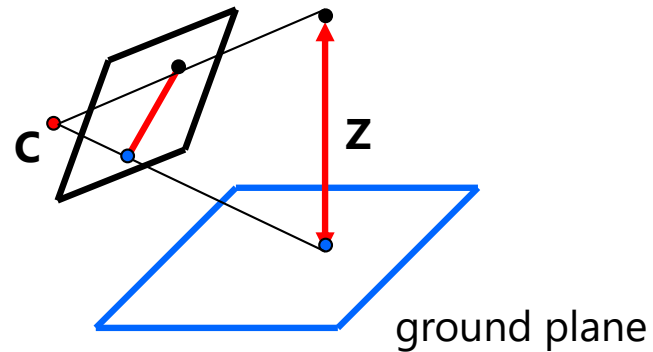
Measuring height



Measuring height without a ruler?



Measuring height without a ruler



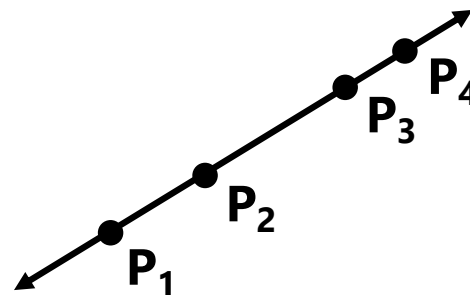
Compute Z from image measurements

- Need more than vanishing points to do this

The cross ratio

- A Projective Invariant
 - Something that does not change under projective transformations (including perspective projection)

The *cross-ratio* of 4 collinear points



$$\frac{\|P_3 - P_1\| \|P_4 - P_2\|}{\|P_3 - P_2\| \|P_4 - P_1\|}$$

$$P_i = \begin{bmatrix} X_i \\ Y_i \\ Z_i \\ 1 \end{bmatrix}$$

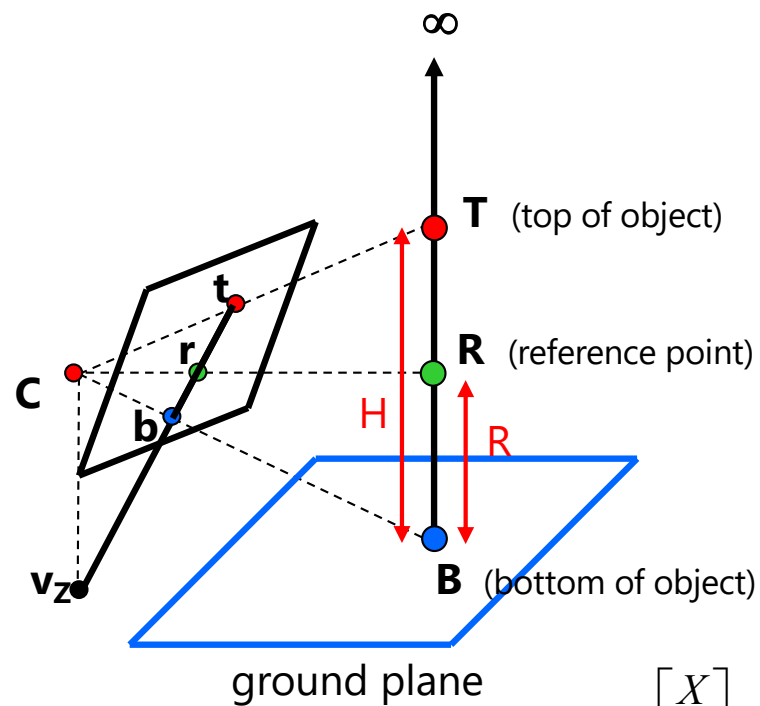
Can permute the point ordering

- $4! = 24$ different orders (but only 6 distinct values)

This is the fundamental invariant of projective geometry

$$\frac{\|P_1 - P_3\| \|P_4 - P_2\|}{\|P_1 - P_2\| \|P_4 - P_3\|}$$

Measuring height



scene points represented as $\mathbf{P} = \begin{bmatrix} X \\ Y \\ Z \\ 1 \end{bmatrix}$

image points as $\mathbf{p} = \begin{bmatrix} x \\ y \\ 1 \end{bmatrix}$

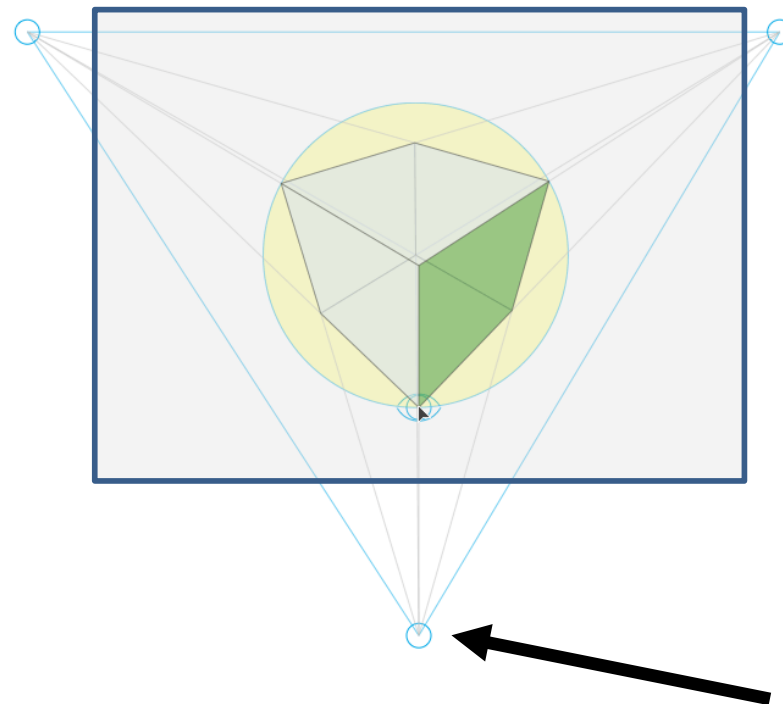
$$\frac{\|\mathbf{T} - \mathbf{B}\| \|\infty - \mathbf{R}\|}{\|\mathbf{R} - \mathbf{B}\| \|\infty - \mathbf{T}\|} = \frac{H}{R}$$

scene cross ratio

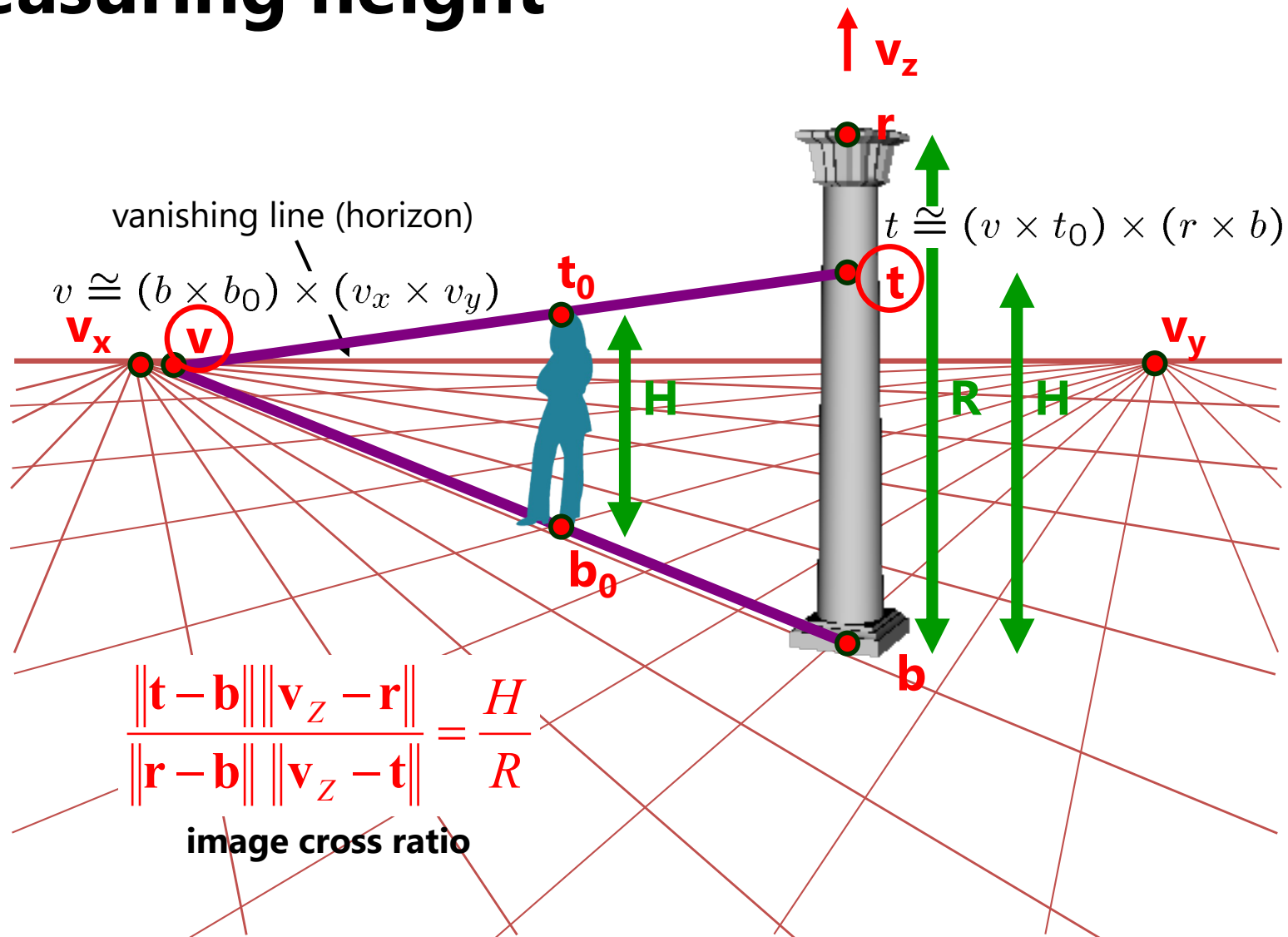
$$\frac{\|\mathbf{t} - \mathbf{b}\| \|\mathbf{v}_z - \mathbf{r}\|}{\|\mathbf{r} - \mathbf{b}\| \|\mathbf{v}_z - \mathbf{t}\|} = \frac{H}{R}$$

image cross ratio

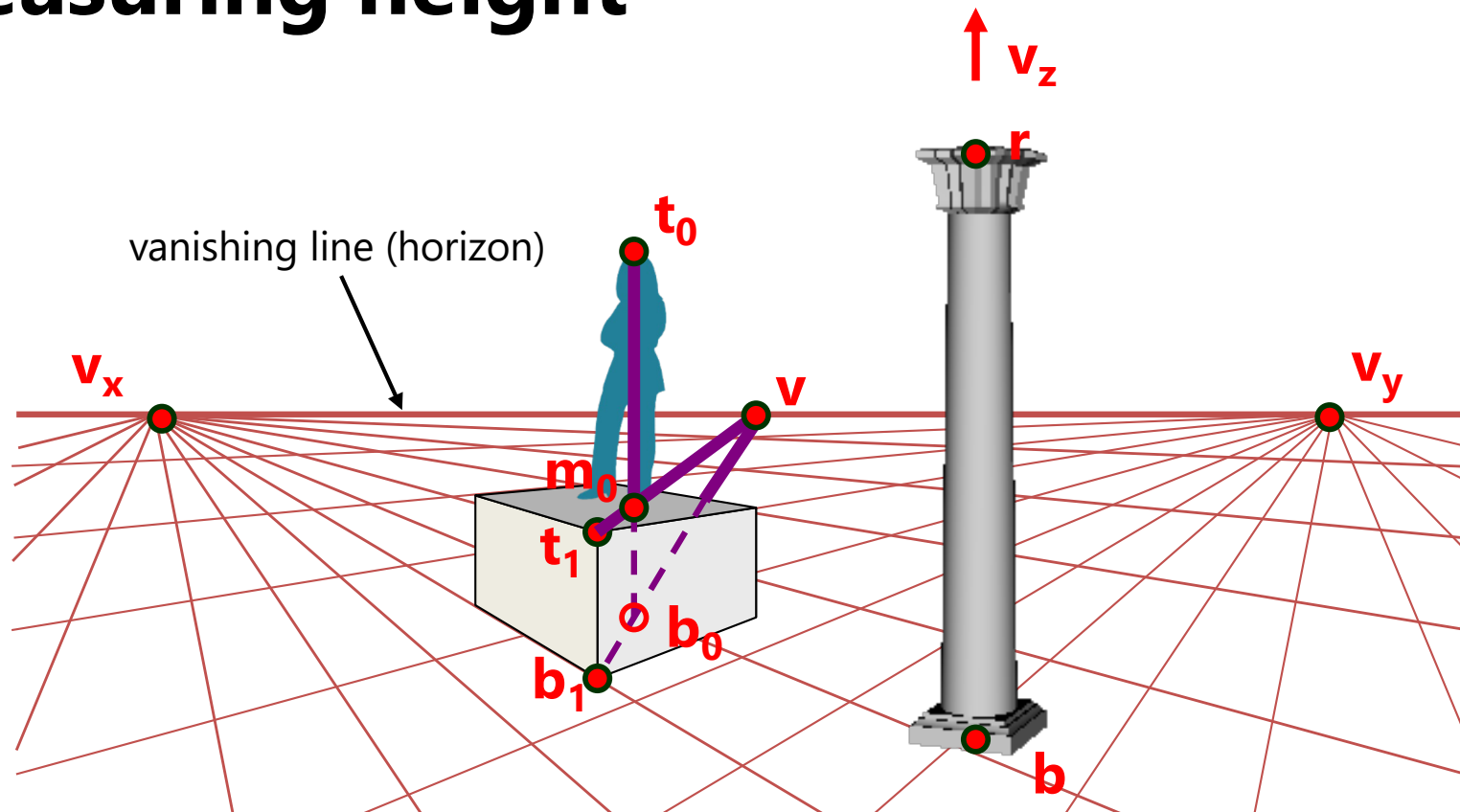
Finding the vertical (z) vanishing point



Measuring height



Measuring height



What if the point on the ground plane b_0 is not known?

- Here the person is standing on the box, height of box is known
- Use one side of the box to help find b_0 as shown above

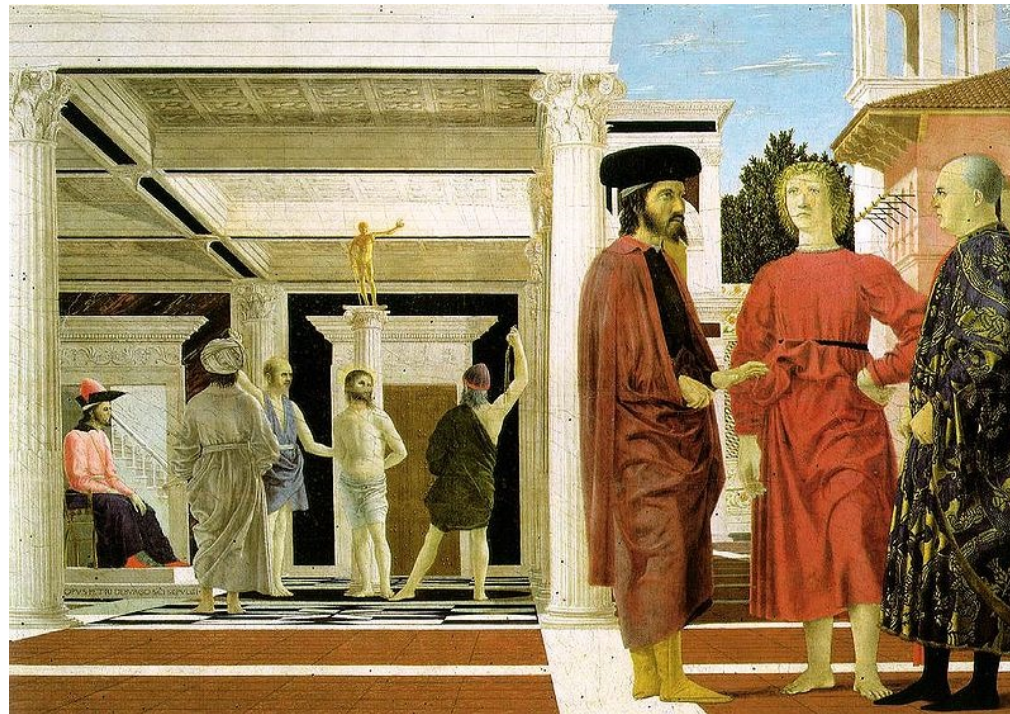
3D modeling from a photograph



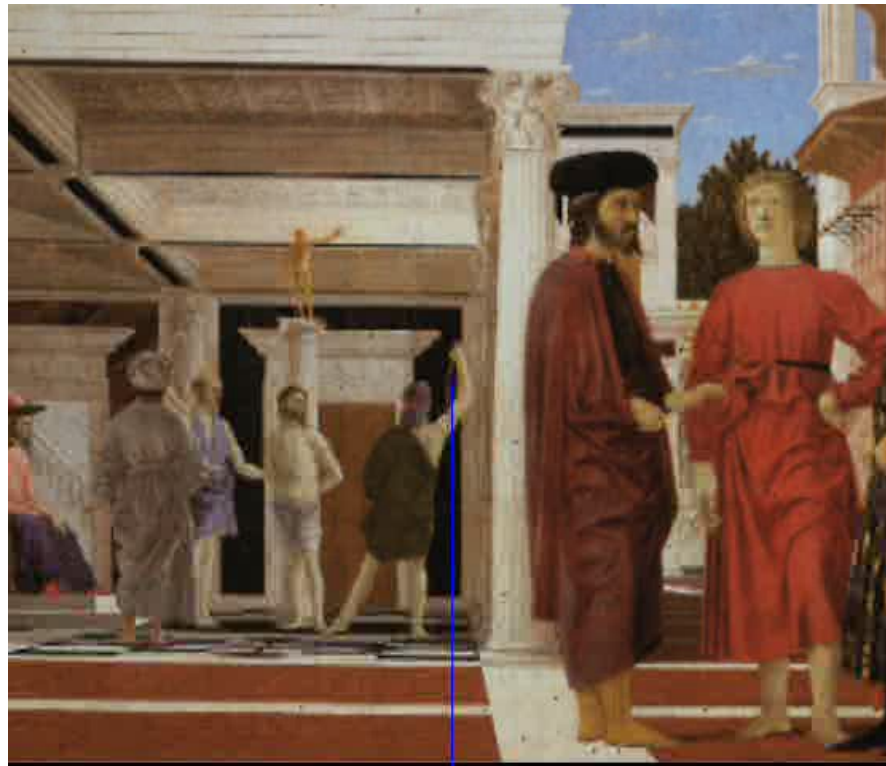
3D modeling from a photograph



3D modeling from a photograph



3D modeling from a photograph



3D modeling from a photograph

